

## PSE 32 - Shaft 14 mm hollow

- Absolute measuring system
- Position control for direct connection to a control module
- Space-saving, compact design
- Galvanically separated supply voltages between control and motor and bus
- Durable EC-motor
- Extremely accurate positioning due to measurement of the position at the output side
- Bus interfaces simplify start-up and wiring complexity
- Address may be set using the bus or an address switch (not for IO-Link)
- Baud rate set via switch
- Status messages retrievable via bus
- Partial safety function for STO (Safe Torque Off)



Dimensions in mm.

**Type:** Horizontal

**Nominal Torque (Nm):** 2; 5; 10; 18

**Nominal Speed (rpm):** 17; 30; 68; 150

**Nominal Voltage (V DC):** 24 ( $\pm 10\%$ )

**Nominal Current (A):** 3.1

**Output Shaft (mm):** 14

**Output Shaft Type:** Hollow

**BUS Communication:** Can Open (CA); Profi Bus (DP); Device Net (DN); Modbus (MB); IO-Link (IO); ProfiNet (PN); Sercos (SE); EtherCat (EC); Ethernet IP (EI); PowerLink (PL)

**Electrical connection:** "Standard; with jog keys; 1 connector Y-encoded or 1 connector Y-encoded with jog keys"

**Protection Class:** IP54; IP65

**Motor:** EC-motor

**Supply Voltage:** 24 V DC  $\pm 10\%$  galvanically separated between control and motor and bus

**Measurement System:** Absolute, optical-magnetic

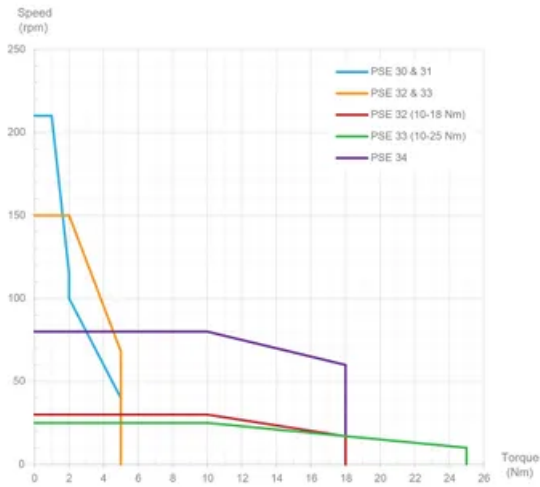
**Accuracy:**  $\pm 0.9^\circ$

**Intermittence:** 30% (basis time 300 s)

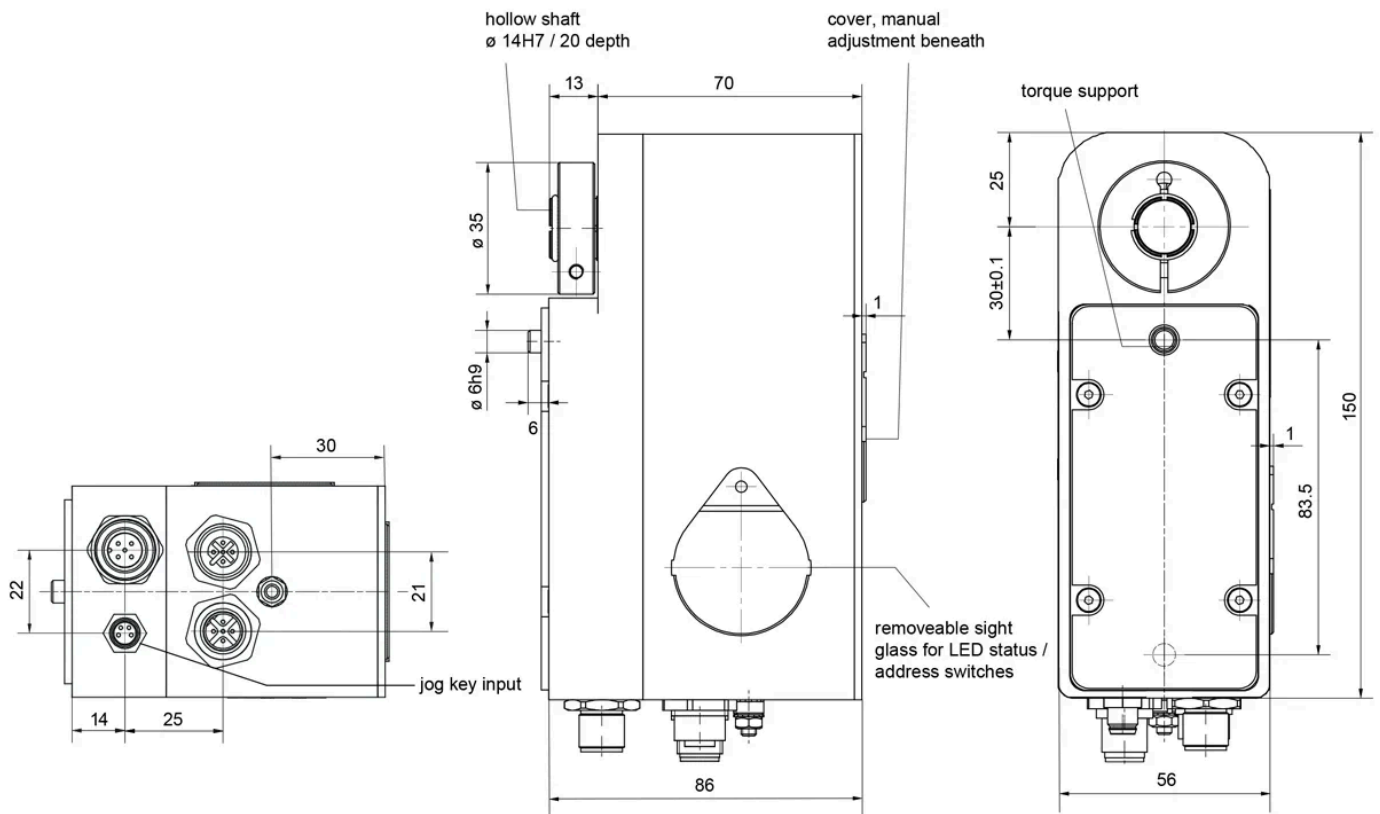
**Manual Adjustment:** Standard

**Brake:** Optional (holding brake)

Performance Curve - Direct Drives PSE



## General Data



Designation	Nominal Torque (Nm)	Nominal Speed (rpm)	Nominal Current (A)	Self-holding Torque (Nm)	Positioning Range (rot.)
PSE 322-14	2	150	3.1	1	250
PSE 325-14	5	68	3.1	2.5	250
PSE 3210-14	10	30	3.1	5	250
PSE 3218-14	18	17	3.1	9	250